

Large-Scale Differential Variational Inequalities for Heterogeneous Materials:

An introduction to a new SciDAC-e project in support of the



Center for Materials Science of Nuclear Fuel

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Motivation: Microstructure Evolution in Materials

- **Differential Variational Inequalities (DVIs) arise in CMSNF models**
 - **Phase Field Approach:** Modeling microstructure at the mesoscale
 - Diffuse boundary between phases must be localized: use double obstacle potentials to generate free energy functional: results in a DVI
- **Challenges**
 - Lack of software for large-scale DVIs
 - Prevailing (non-DVI) approach approximates dynamics of phase variable using a smoothed potential: Stiff problem and undesirable physical artifacts
 - phase field variable does not have a compact support
 - boundary between phases is no longer localized



Vision of our SciDAC-e Project

- **Broad aim:** Develop advanced numerical techniques and scalable software for DVIs for the resolution of large-scale, heterogeneous materials problems
- Collaboration among CMSNF and TOPS researchers
- **Goals**
 - Create software for resolving mesoscale models of heterogeneous materials with a methodology that removes the modeling compromises that have been needed up to this point
 - Leverage emerging extreme-scale computing resources to enable simulations with billions of discretization nodes (or thousands of grains) and thus to develop a predictive capability for virtually any phenomenon of interest concerning radiation in nanostructures



Center for Materials Science of Nuclear Fuel



Towards Optimal Petascale Simulations

PI: David Keyes, Columbia Univ.
www.scalablesolvers.org

3-Pronged Approach

- **Model heterogeneous materials with DVIs**
 - Led by M. Anitescu and A. El-Azab
 - Model phase field equations as DVIs for all classes of materials that confront CMSNF
- **Apply scalable algorithms for the resulting variational inequalities (VIs)**
 - Led by T. Munson
 - Resolve the subproblems of the time-stepping procedure using
 - Semismooth, active set, and interior-point approaches
 - Employ specialized multigrid techniques that map the active set between levels without impeding optimal convergence and scalability
- **Develop flexible, scalable VI software**
 - Led by L. C. McInnes and B. Smith
 - Build on infrastructure of PETSc and TAO (two TOPS numerical libraries)
 - Leverage work by TOPS colleagues Xiao-Chuan Cai and David Keyes in complementary SciDAC-e project, *Scalable Solvers for Fully Coupled Nuclear Fuel Modeling*

Heterogeneous Materials Modeling with DVIs

- Use a phase field model to describe microstructure:
 - Use a **diffuse boundary** representation for the region between phases; this may be more suitable physically for the scales used, and better handles phase disappearance. The boundary is defined by means of a phase variable $-1 \leq \phi \leq 1$; the interface region is the one where $-1 < \phi < 1$
 - Write a free energy functional that includes a double obstacle potential (which allows for finite boundary region extension); in turn the inequalities on the phase field variable have to be treated by hard constraints.
 - Write the dynamics of the phase configuration using the mobilities provided by the CMSNF. Due to the double obstacle potential, these have a free boundary; the resulting equations are Allen-Cahn and Cahn-Hilliard with free boundary.
 - We discretize in time, enforcing the free boundary configuration **implicitly**. This results in a variational inequality to be solved at each step.

DVI Formulation

■ Differential Variational Inequalities

- Arise whenever both dynamics and inequalities/switching appear in model
- Mixture of differential equations and variational inequalities

$$\begin{aligned}y' &= f(t, y(t), x(t)) \\ x(t) &\in SOL(K; F(t, y(t), \cdot)) \\ y(0) &= y_0\end{aligned}$$

$$x \in SOL(K; F(t, y, \cdot)) \Leftrightarrow (\tilde{x} - x)^T F(t, y, x) \geq 0, \forall \tilde{x} \in K$$

- In the case of complementarity, $K = \mathbb{R}_+^n$

$$\begin{aligned}y' &= f(t, y(t), x(t)) \\ 0 &\leq x(t); F(t, y(t), x(t)) \\ 0 &= x(t)^T F(t, y(t), x(t)) \\ y(0) &= y_0\end{aligned}$$



Scalable Algorithms for Variational Inequalities

- Build on capabilities in the Toolkit for Advanced Optimization (TAO)
 - www.mcs.anl.gov/tao
 - Parallel software for numerical optimization, uses PETSc for linear algebra
- Focus:
 - Semismooth methods
 - Begin with box-constrained VI: semismooth reformulation using nonlinear complementarity problem
 - Multigrid semismooth methods
 - Active set methods
 - Interior-point methods

Semismooth Reformulation for Box-Constrained Variational Inequalities

- Nonlinear complementarity problem:

$$0 \leq x \perp F(x) \geq 0,$$

where \perp implies componentwise that at the solution, either

$$x_i = 0 \text{ or } F_i(x) = 0$$

- Reformulate using a function $\phi(a,b)$ with the property that

$$\phi(a,b) = 0 \Leftrightarrow 0 \leq a \perp b \geq 0$$

Fischer-Burmeister function: $\phi(a,b) = a + b - \sqrt{a^2 + b^2}$

- Thus, we solve

$$\Phi(x, F(x)) = 0, \text{ where } \Phi_i(x, F(x)) = \phi(x_i, F_i(x))$$

using a globalized Newton method

Scalable Software for Variational Inequalities

- Develop a new VI problem class in PETSc (www.mcs.anl.gov/petsc)
 - Develop a VI solver interface
 - Develop 3 complementary VI solver implementations based on
 - Semismooth algorithms
 - Active set methods
 - Interior point methods
- Build on SNES component of PETSc: Scalable Nonlinear Equations Solvers
 - Preconditioned Newton-Krylov methods with line search or trust region variants
 - User provides code for nonlinear function evaluation
 - User can provide code for Jacobian computation (or alternatively PETSc can compute using sparse finite differences or automatic differentiation)
 - SNES overview: see <http://www.mcs.anl.gov/~curfman/docs/mcinnis-siam09.pdf>
- Box-constrained VI: Require user to provide bounds on variables for SNES; otherwise, interface will remain largely unchanged



Modeling Issues Specific to CMSNF Applications

- Issues in adopting phase field approach to model microstructure evolution under irradiation conditions
 - Selection of phase field variables and representation of free energy functional in terms of these variables
 - Explicit representation of radiation environment into phase field kinetic equations
- Test cases
 - Single-void dynamics in UO_2
 - Multiple-void dynamics in UO_2
 - Nucleation and growth of void ensembles

Personnel Update

- New hire:
 - Lei Wang, Ph.D. in Applied and Interdisciplinary Mathematics from the University of Michigan, May 2010
 - Will begin working at Argonne on Sept 20, 2010
 - Focusing on modeling, with M. Anitescu and A. El-Azab
- In the process of interviewing candidates for algorithms/software postdoc position
- Support for 2 graduate students during summer 2011
- Possibly other student/faculty/research visitors also